



YK-ZR Linear Rotary Motor



◎ YK-ZR series linear rotary motor has the following characteristics:

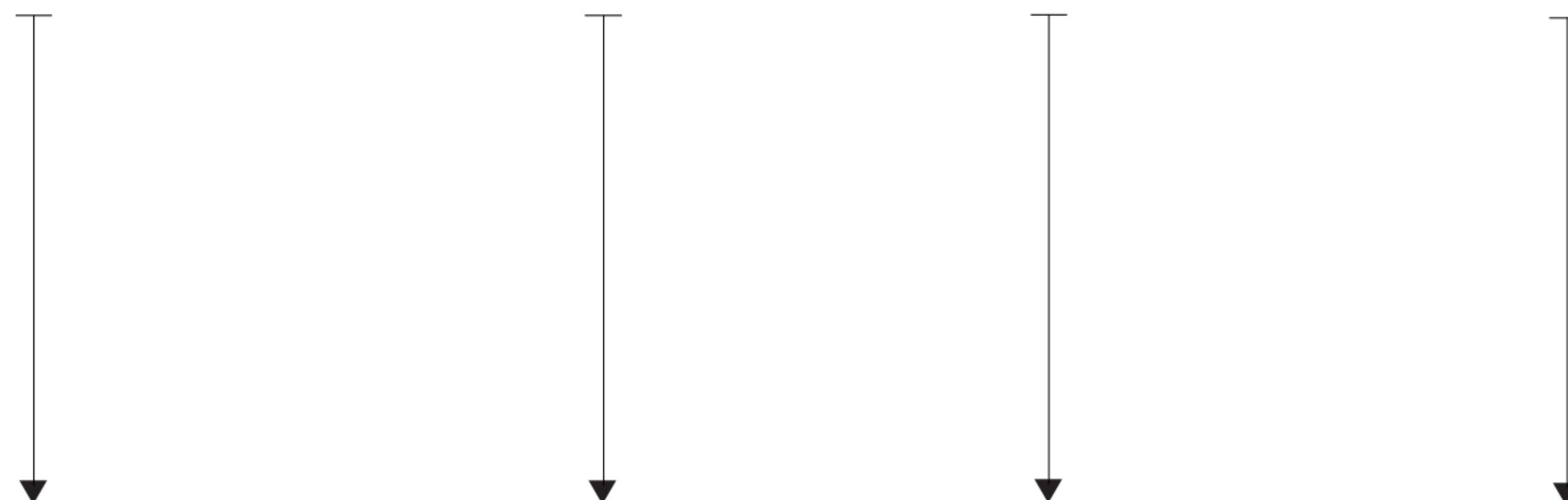
- ① Modular design, installation reference surface and shaft end positioning do not require mechanical position calibration
- ② Mounting position accuracy XY: $\pm 1\mu\text{m}$, angle accuracy Z: $\pm 0.001^\circ$; precision fitting, high-speed continuous action
- ③ Force control stability accuracy: $\pm 5.0\text{g}$ (0.05N), soft landing function with lighter force contact, will not damage the chip or leave marks on the chip
- ④ Hollow + customizable Z axis, reserved air pipe interface, vacuum suction plug and play
- ⑤ Can perform linear and rotational motion at the same time, or can achieve linear motion or rotational motion separately

◎ Application range:

Suitable for SMT, plug-in machines, patch machines, semiconductors, photovoltaic panels and optical devices 3C products assembly and testing and other automation equipment.

◎ YK-ZR series linear rotary motor naming rules

YK-ZR - 20 25 - M10



Linear rotary motor

Total motor thickness

Maximum stroke

Encoder Type

20mm

25mm

M05: 0.5 μm , magnetic coding (standard)

28mm

50mm

M10: 1 μm , magnetic coding

E05: 0.5 μm , optical coding

EA: analog

The standard cable length is 0.3m

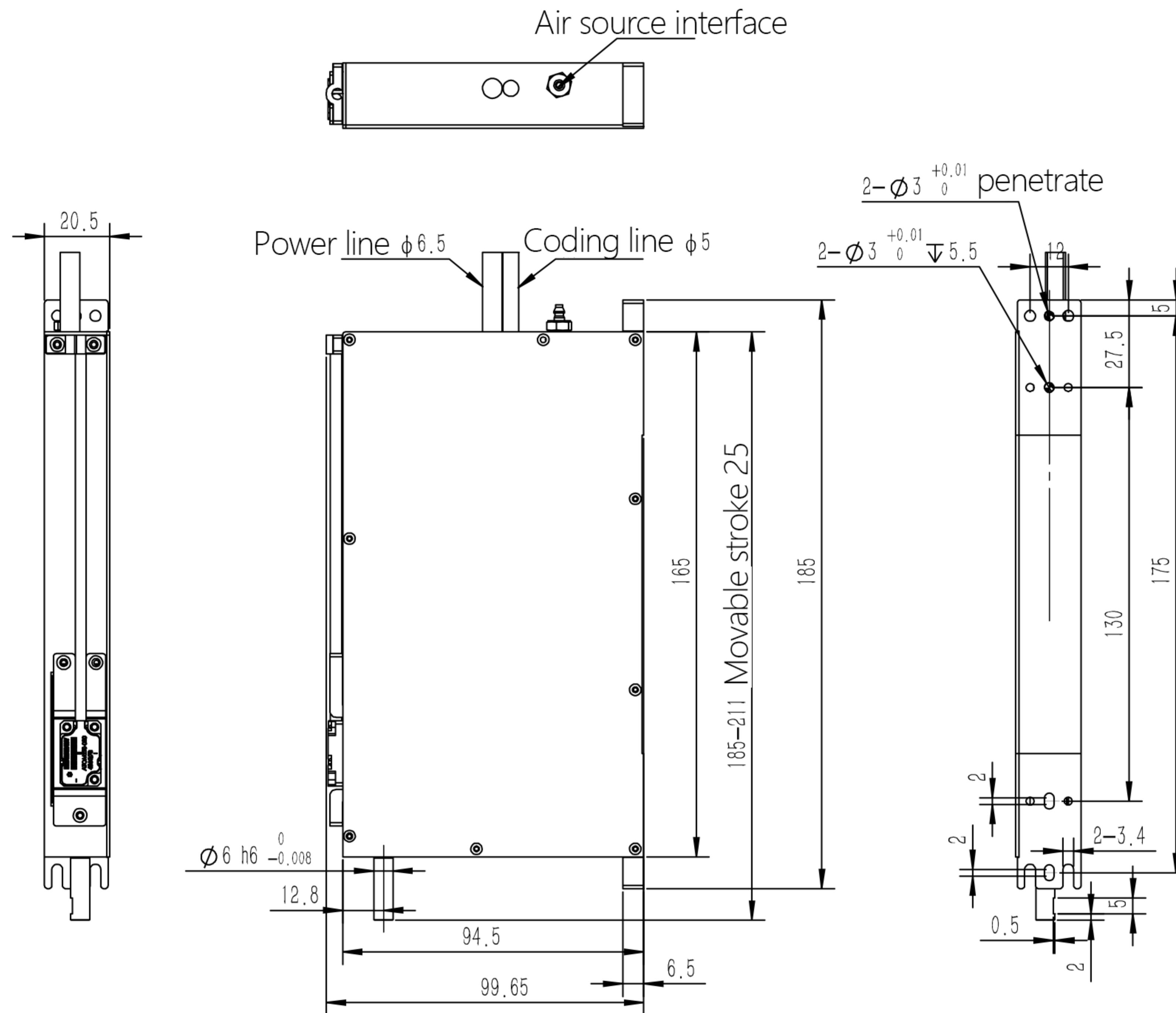


◎ YK-ZR Linear Rotary Motor Catalog

- Y K - Z R - 2025 ······ 05
- Y K - Z R - 2850 ······ 06

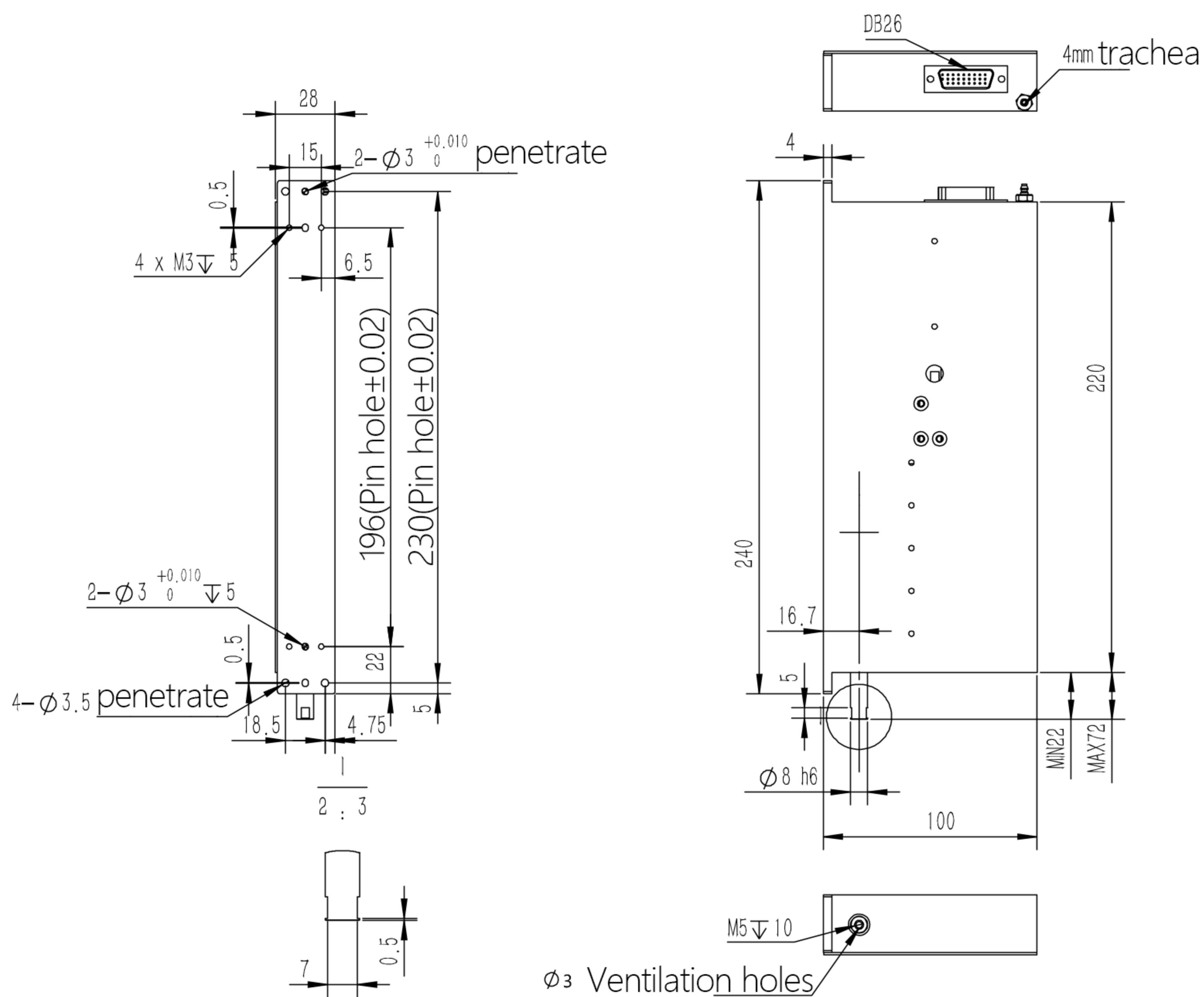
YK-ZR Linear Rotary Motor

◎ Y K - Z R - 2025



Linear parameters			Rotation parameters		
Parameters	Value	Unit	Parameters	Value	Unit
Valid itinerary	25	mm	Rated torque	10	mNm
resolution	0.5,customizable	μm	Instantaneous torque	43.8	mNm
Continuous thrust	8	N	encoder	4096	Wire
peak thrust	15	N	Rated current	1.3	Arms
continuous current	1.2	A	instantaneous current	3.3	Arms
Peak current	2.5	A	Torque constant	13.2	mNm/A
force constant	5.4	N/A	Voltage	24 ~ 48	V
DC resistance	13.5	Ω	Line resistance	23.78	Ω
inductance	2.5	mH	Line inductance	1.96	mH
Voltage	24~48	V	Rated speed	3000	rpm

◎ YK-ZR - 2850



Straight line parameters			Rotational parameters		
Parameters	Value	Unit	Parameters	Value	Unit
Valid itinerary	50	mm	Rated torque	95	mNm
resolution	0.5,customizable	μm	Instantaneous torque	285	mNm
Continuous thrust	22	N	encoder	2048	Wire
peak thrust	66	N	Rated current	4	Arms
continuous current	1.5	A	instantaneous current	11.2	Arms
Peak current	4.5	A	Torque constant	26	mNm/A
force constant	14.67	N/A	Voltage	24 ~ 48	V
DC resistance	9.8	Ω	Line resistance	0.907	Ω
inductance	0.77	mH	Line inductance	0.2	mH
Voltage	24~48	V	Rated speed	4000	rpm